

## M-714 Nanometer-Precision Linear Stage Heavy-Duty Precision Hybrid DC/Piezo Drive with High Guiding-Accuracy



Hybrid Z-positioner M-714.HD

- **Simultaneous Control of Piezo-Flexure Drives & DC-Servo/Ballscrew Drives**
- **7 mm Vertical Travel Range, 10 kg Load Capacity**
- **High Holding Forces with Minimum Power Consumption**
- **Integrated Precision Linear Encoder Provides 2 nm Resolution**
- **Active Backlash Compensation and Stick/Slip Compensation**
- **Frictionless Piezo Drive and Flexure-Decoupled Ballscrew**
- **Millisecond Settling Time to Nanometer Precision**

The M-714 was designed from the ground up to use the hybrid drive technology. The hybrid design overcomes the limitations of conventional precision positioning systems by combining the well-known advantages of piezo-flexure-drives (unlimited resolution and very rapid response) with the long travel ranges and high holding forces of a servo-motor/ballscrew arrangement. The M-714 can position loads up to 10 kg with nanometer precision over 7 mm in vertical or horizontal direction. Com-

pared to high-resolution magnetic linear drives, the hybrid principle allows high holding forces with minimum power consumption, without counterbalancing the load. The angular deviation is less than  $\pm 10 \mu\text{rad}$  over the entire travel range of 7 mm.

### Long Travel Ranges with Nanometer Precision

The challenge of implementing hybrid technology is not only the positioning stage design, but also the use of high-resolution sensors over large travel ranges, the processing of the resulting high-frequency signals and the design of special control algorithms to take full advantage of the hybrid concept.

On the mechanical side, this is accomplished by decoupling the moving platform from the positioner's motor-ballscrew-

drive by frictionless flexures and stiff, highly responsive piezo actuators.

Due to its high stiffness and instantaneous, sub-millisecond range response, the integrated piezo flexure drive provides active stick/slip compensation during startup and settling and is the key to achieving consistent and repeatable nanometer level positioning increments. It also cancels out motion irregularities caused by the ball screw and significantly improves velocity control.

Servo-control of the system employs a single high-resolution position feedback sensor (direct metrology) which means that the inherent piezo precision is available over the entire travel range of 7 mm, and longer travel ranges are basically feasible. The resolution and the positioning accuracy mainly depend on the choice of the feedback sensor.

### Hybrid Controller Technology is Key to Success

PI's highly specialized C-702 hybrid nanopositioning controller (see p. 4-118) compares the actual platform position (by

### Ordering Information

**M-714.2HD**  
Ultra-High Precision Hybrid Nanopositioning Stage, 7 mm Travel, 2 nm Linear Encoder Resolution

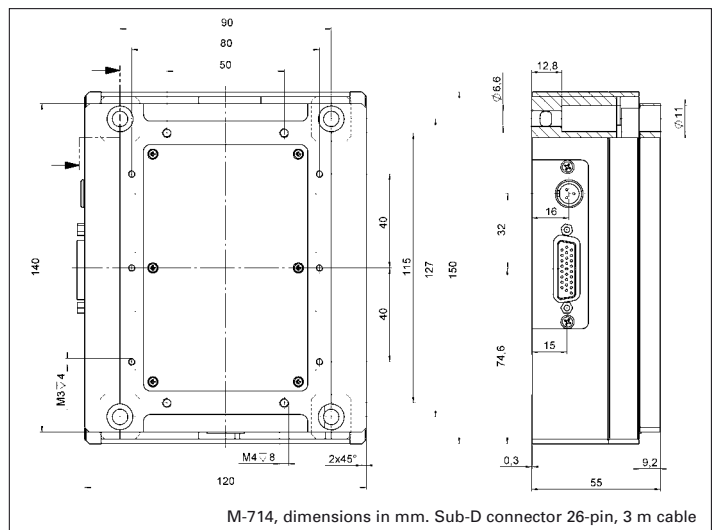
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reading the integrated linear encoder) with a calculated, smooth trajectory in real time. Its complex control algorithms continuously actuate both the piezoelectric and servo motor drives in a way to provide the best possible overall performance.

This makes hybrid systems ideal for applications where extremely smooth motion is required, where the position of an incident needs to be read and reformed precisely, or where an externally specified target position needs to be hit within a few nanometers, such as in surface inspection or metrology.

### Notes

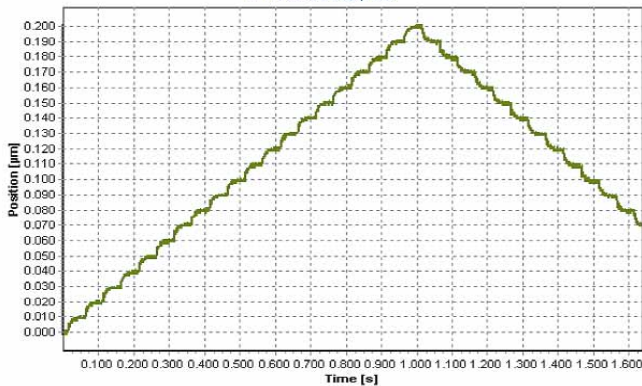
The M-714.2HD positioning system is optimized for vertical operation. If horizontal operation is intended, please note with your order.



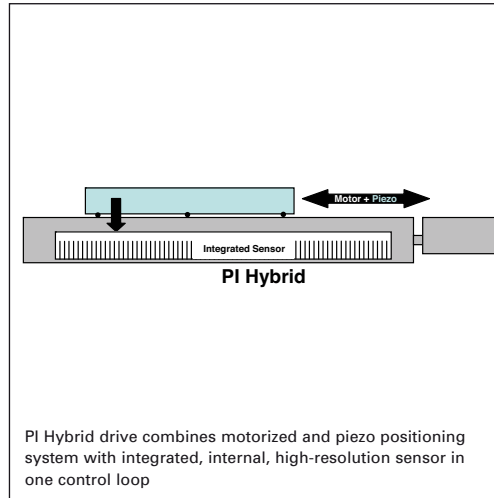
M-714, dimensions in mm. Sub-D connector 26-pin, 3 m cable

### Application Examples

- Surface Inspection
- Microscopy
- Laser technology
- Interferometry
- Metrology



10 nm steps of an M-714 stage, as commanded by a C-702 digital controller and measured by an interferometer



PI Hybrid drive combines motorized and piezo positioning system with integrated, internal, high-resolution sensor in one control loop

## Technical Data

	M-714.2HD
<b>Motion and positioning</b>	
Travel range	7 mm
Integrated sensor	Linear encoder
Sensor resolution	0.002 µm
Design resolution	0.002 µm
Min. incremental motion	0.004 µm
Hysteresis at the platform	0.01 µm
Unidirectional repeatability	0.01 µm
Accuracy	<0.05 µm
Pitch	±10 µrad
Yaw	±10 µrad
Max. velocity	0.2 mm/s
Origin repeatability	1 µm
<b>Mechanical properties</b>	
Drive screw	Leadscrew
Guiding	Crossed-roller bearings
Screw pitch	1 mm/rev.
Gear ratio	80:1
Belt drive transmission ratio	3:1
Max. push/pull force	100/100 N
Self inhibition	100 N
Max. lateral force	200 N
<b>Drive properties</b>	
Drive type	Hybrid drive: DC-motor with low-inertia, flexure-decoupled and piezo actuated stage platform
Motor type	DC-motor, gearhead
Operating voltage (motor)	24 V
Electrical power	13 W
Piezo drive type	PICMA® Multilayer piezo with flexure
Piezo voltage	±36 V
Limit and reference switches	Hall-effect
<b>Miscellaneous</b>	
Operating temperature range	-20 °C to +65 °C
Material	Al (black anodized)
Mass	2.1 kg
Recommended controller/driver	C-702 hybrid motor controller (p. 4-118)